

# Motor Protection Relay REM 610

## Product Guide



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## 1. Description

The motor protection relay REM 610 is part of the RE\_ 610 series of numerical relays for the protection and supervision of utility substations, industrial switchgear and equipment.

The motor protection relay REM 610 is primarily targeted at protecting large asynchronous low-voltage motors and small and medium-sized high-voltage asynchronous motors. REM 610 handles electrical fault conditions during motor start up, normal operation, idling, and cooling down at standstill, e.g. in pump, fan, mill or crusher applications.

## 2. Protection functions

The relay offers many integrated protection functions for the protection of motors. The thermal overload protection, cumulative motor start up supervision, running stall protection, earth-fault protection and loss-of-phase are the key functions of this relay. The coverage of the thermal overload protection can be further enhanced by means of an optional RTD module for direct temperature measurement.

### Protection functions of REM 610

Function / Description	IEC	ANSI
Three-phase thermal overload protection	$\Theta >$	49M
Motor start-up supervision based on thermal stress calculation <sup>a)</sup>	$I_s^2 t_s$	48/14
Three-phase definite time overcurrent protection, low-set stage <sup>a)</sup>	$I_s >$	51/14
Three-phase instantaneous or definite time short circuit protection, high-set stage	$3I >>$	50/51
Inverse-time unbalance protection based on the negative sequence current	$I_2 >$	46
Phase reversal protection	REV	46R
Definite-time undercurrent (loss of load) protection	$3I <$	66
Instantaneous or definite-time earth-fault protection	$I_0 >$	50N/51N
Cumulative start-up time counter and restart inhibit function	$\Sigma t_{si}$	37
Temperature protection using RTD sensors or thermistors	ThA>, ThB>	49/38
Circuit-breaker failure protection	CBFP	62BF
Lockout relay function		86

<sup>a)</sup> Mutually exclusive functions

The relay can be used with both circuit-breaker controlled and contactor-controlled drives. REM 610 can also be used for the protection of cables' feeders and distribution transformers that require thermal overload protection besides overcurrent, earth-fault and phase unbalance protection.

The numerical motor protection relays of the RE\_ 610 series support a wide range of standard communication protocols, among them the IEC 61850, IEC 60870-5-103, Modbus and Profibus.

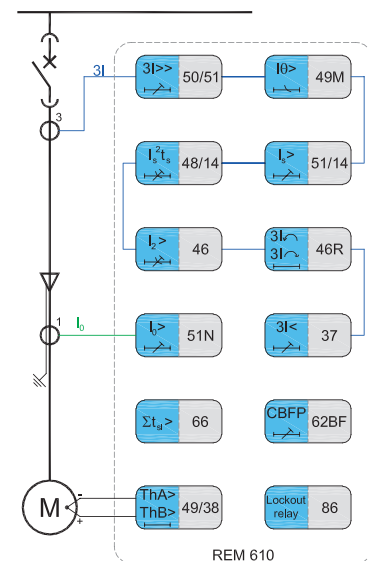


Fig. 1 Protection function overview of REM 610

### 3. Measurement

The relay physically measures the phase currents and the residual current. From the phase currents, the relay calculates the thermal overload and the negative-phase-sequence current of the protected motor or generator. REM 610 also measures a number of characteristic currents of the protected object during start-up and duty operation. Further, by means of an optional measurement card, the relay can directly measure up to eight temperatures via six RTD and two thermistor type sensors.

The values measured can be accessed locally via the user interface on the relay front panel or remotely via the serial communication interface on the rear panel of the relay.

### 4. Disturbance recorder

The relay is provided with a built-in battery backed-up digital disturbance recorder for four analog signal channels and eight digital signal channels. The analog channels can be set to record the curve form of the currents measured. The digital channels can be set to record external or internal relay signals, e.g. the start or trip signals of relay stages, external blocking or control signals. Any digital relay signal such as a protection start or trip signal, or an external relay control signal can be set to trigger the recording. The recordings are stored in a non-volatile memory from which the data can be uploaded for subsequent fault analysis.

### 5. Event recorder

To provide network control and monitoring systems with bay level event logs, the relay incorporates a non-volatile memory with capacity of storing 100 event codes including

the time stamps. The non-volatile memory retains its data also in case the relay temporarily loses its auxiliary supply. The event log facilitates detailed pre- and post-fault analyses of the faults and disturbances.

### 6. Trip-circuit supervision

The trip-circuit supervision continuously monitors the availability and operability of the trip circuit. It provides open circuit monitoring both when the circuit breaker is in its closed and in its open position. It also detects the loss of circuit-breaker control voltage.

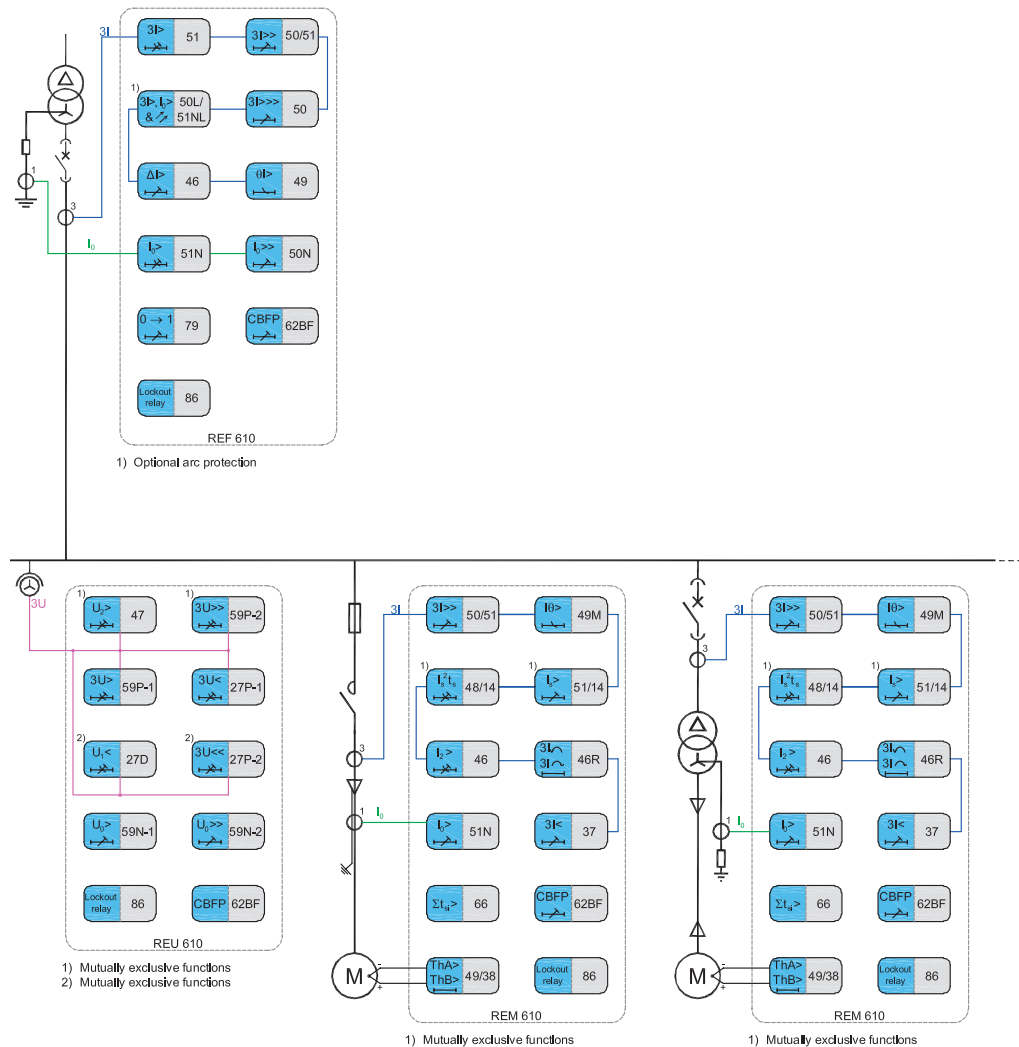
### 7. Self-supervision

The relay's built-in self-supervision system continuously monitors the state of the relay hardware and the operation of the relay software. Any fault or malfunction detected will be used for alerting the operator. When a permanent relay fault is detected, the protection functions of the relay will be completely blocked to prevent any incorrect relay operation.

### 8. Inputs/Outputs

- Four current transformers
- Two digital inputs
- Three additional digital inputs on an optional RTD module
- Three normally open heavy duty output contacts
- Two change-over signal output contacts
- One dedicated IRF contact
- Input/output contacts freely configurable

## 9. Application



*Fig 2. REM 610 can be used for the protection of both circuit-breaker controlled and contactor controlled motor drives. In the contactor controlled motor drive application, the protection also covers the feeder cable and the cable box. The CB controlled application features a transformer and motor drive application. The load side of the transformer is earthed via a resistor, which enables current measuring earth-fault protection to be used. In both applications, the critical motor temperatures are supervised through direct temperature measurement via embedded sensors.*

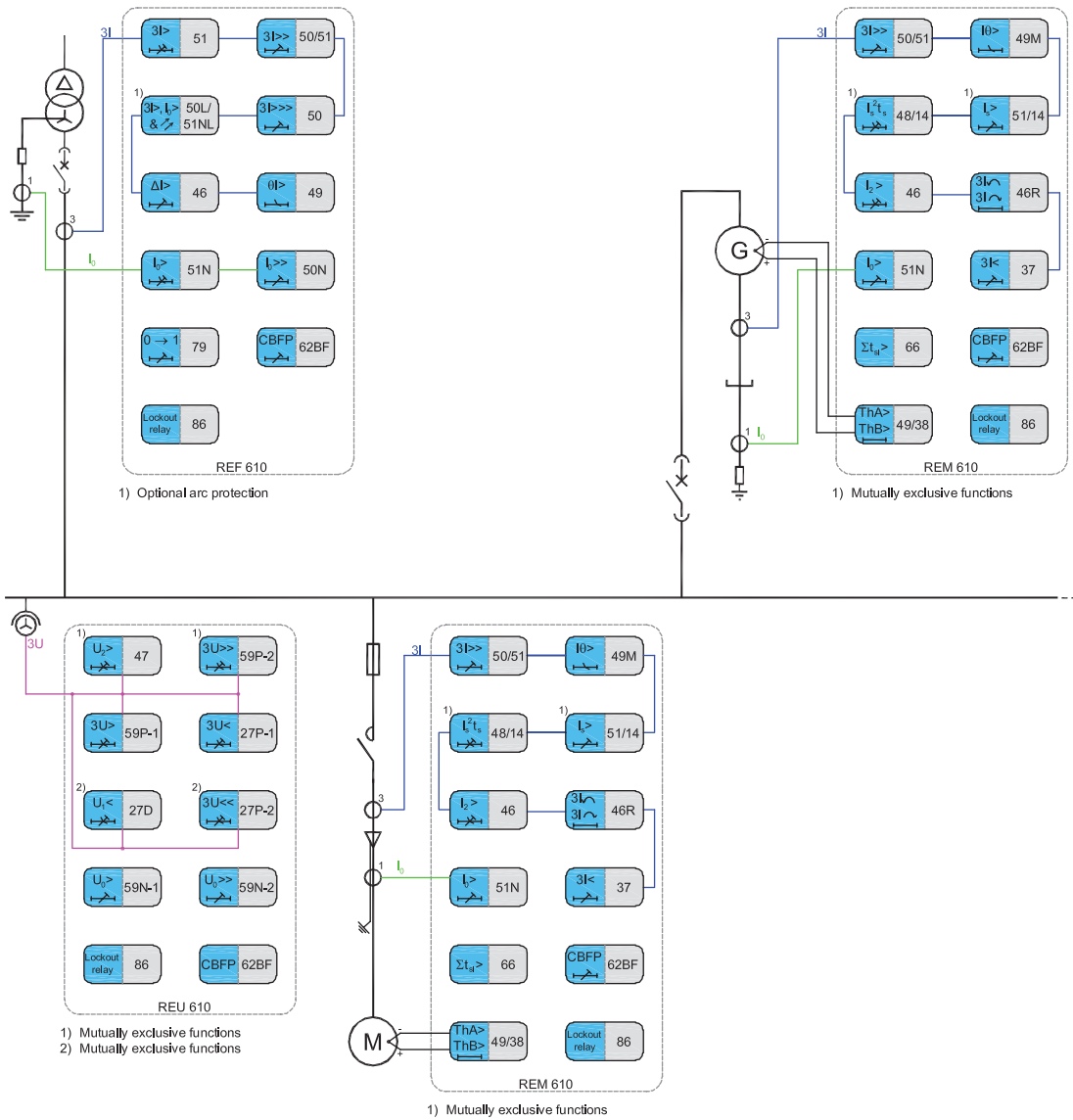












Fig. 3 REM 610 provides a full range of protection functions for the large low-voltage motors and from small to medium sized high-voltage motors. REM 610 is also used for the protection of small asynchronous power generators, for which the relay offers short-circuit and time overcurrent protection, thermal overload protection, phase unbalance and stall protection, and stator earth-fault protection. Further, the relay features direct temperature measurement via embedded sensors in the generator winding or bearings.

## 10. Communication

The protection relays are connected to the fibre-optic communication bus directly or via bus connection modules and gateways. The bus connection module converts the relay's electrical signals to optical signals for the communication bus and, vice versa, the communication bus' optical signals to electrical signals for the relay.

### Optional communication modules and protocols

Protocol	Plastic fibre	Plastic/Glass fibre	RS-485	Bus connection modules and gateways
SPA	X	X	X	 IED
IEC 60870-5-103	X	X	X	
Modbus (RTU and ASCII)	X	X	X	
IEC 61850	X	X	-	  IED + SPA-ZC 402
LON	-	-	X	  IED + SPA-ZC 102
	X	X	-	   IED + SPA-ZC 21 + SPA-ZC 102
Profibus	-	-	X	  IED + SPA-ZC 302

## 11. Technical data

### Dimensions

Width	frame	177 mm,
	case	164 mm
Height	frame	177 (4U),
	case	160 mm
Depth	case	149.3 mm
Weight	relay	3.5 kg
	spare unit	1.8 kg

### Power Supply

Type:	REM 610CxxHxxx	REM 610CxxLxxx
$U_{aux}$ rated	$U_r = 100/110/120/220/240$ V AC $U_r = 110/125/220/250$ V DC	$U_r = 24/48/60$ V DC
$U_{aux}$ variation (temporary)	85...110% x $U_r$ (AC) 80...120% x $U_r$ (DC)	80...120% x $U_r$ (DC)
Burden of auxiliary voltage supply under quiescent ( $P_q$ )/operating condition	<9 W/13 W	
Ripple in DC auxiliary voltage	Max 12% of the DC value (at frequency of 100 Hz)	
Interruption time in the auxiliary DC voltage without resetting the relay	<50 ms at $U_{aux}$ rated	
Time to trip from switching on the auxiliary voltage <sup>a)</sup>	<350 ms	
Internal over temperature limit	+100 °C	
Fuse type	T2A/250 V	

a) Time to trip of stages I>>.

### Energizing inputs

Rated frequency	50/60 Hz ± 5 Hz	
Rated current, $I_n$	1 A	5 A
Thermal withstand capability:		
• continuously	4 A	20 A
• for 1 s	100 A	500 A
• for 10 s	25 A	100 A
Dynamic current withstand:		
• half-wave value	250 A	1250 A
Input impedance	<100 mΩ	<20 mΩ



### Measuring range

Measured currents on phases $I_{L1}$ , $I_{L2}$ and $I_{L3}$ as multiples of the rated currents of the energizing inputs	0...50 x $I_n$
Earth-fault current as a multiple of the rated current of the energizing input	0...8 x $I_n$

### Digital Inputs

Rated voltage	DI1...DI2	DI3...DI5 (optional)
<ul style="list-style-type: none"> <li>• REM 610BxxHxxx Activating threshold</li> <li>• REM 610BxxLxxx Activating threshold</li> <li>• REM 610BxxxxMx Activating threshold</li> </ul>	110/125/220/250 V DC Max. 88 V DC (110 V DC -20%)  24/48/60/110/125/220/250 V DC Max. 19,2 V DC (24 V DC -20%)	24/48/60/110/125/220/250 V DC Max. 19,2 V DC (24 V DC -20%)
Operating range		±20% of the rated voltage
Current drain		2...18 mA
Power consumption/ input		<0.9 W

### Signal output SO1

Rated voltage	250 V AC/DC
Continuous carry	5 A
Make and carry for 3.0 s	15 A
Make and carry for 0.5 s	30 A
Breaking capacity when the control-circuit time constant L/R <40 ms, at 48/110/220 V DC	1 A/0.25 A/0.15 A
Minimum contact load	100 mA at 24 V AC/DC

### Signal output SO2 and IRF output

Rated voltage	250 V AC/DC
Continuous carry	5 A
Make and carry for 3.0 s	10 A
Make and carry for 0.5 s	35 A
Breaking capacity when the control-circuit time constant L/R <40 ms, at 48/110/220 V DC	1 A/0.25 A/0.15 A
Minimum contact load	100 mA at 24 V AC/DC

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**Power outputs PO1, PO2 and PO3**

Rated voltage	250 V AC/DC
Continuous carry	5 A
Make and carry for 3.0 s	15 A
Make and carry for 0.5 s	30 A
Breaking capacity when the control-circuit time constant L/R <40 ms, at 48/110/220 V DC (PO1 with both contacts connected in series)	5 A/3 A/1 A
Minimum contact load	100 mA at 24 V AC/DC
Trip-circuit supervision (TCS):	
• Control voltage range	20...265 V AC/DC
• Current drain through the supervision circuit	~1.5 mA
• Minimum voltage over a contact	20 V AC/DC (15...20 V)

**Enclosure class of the flush-mounted relay**

Front side	IP 54
Rear side, top of the relay	IP 40
Rear side, connection terminals	IP 20

**RTD/analogue inputs**

Supported RTD sensors	100 Ω platinum	TCR 0.00385 (DIN 43760)
	250 Ω platinum	TCR 0.00385
	1000 Ω platinum	TCR 0.00385
	100 Ω nickel	TCR 0.00618 (DIN 43760)
	120 Ω nickel	TCR 0.00618
	120 Ω nickel (US)	TCR 0.00672
	10 Ω copper	TCR 0.00427
Supported PTC thermistor range	0...20 kΩ	
Maximum lead resistance (three-wire measurement)	200 Ω per lead	
Isolation	2 kV (inputs to protective earth)	
Sampling frequency	5 Hz	
Response time	<8 s	
RTD/resistance sensing current	Maximum 4.2 mA rms 6.2 mA rms for 10 Ω copper	

**Environmental tests and conditions**

Recommended service temperature range (continuous)	-10...+55°C
Humidity	<95% RH
Limit temperature range (short-term)	-40...+70°C
Transport and storage temperature range	-40...+85°C according to IEC 60068-2-48
Dry heat test (humidity <50%)	According to IEC 60068-2-2
Dry cold test	According to IEC 60068-2-1
Damp heat test, cyclic (humidity >93%)	According to IEC 60068-2-30
Atmospheric pressure	86...106 kPa

**Electromagnetic compatibility tests**

The EMC immunity test level meets the requirements listed below:	
1 MHz burst disturbance test, class III: • Common mode • Differential mode	According to IEC 60255-22-1 2.5 kV 1.0 kV
Electrostatic discharge test, class IV:  • For contact discharge • For air discharge	According to IEC 61000-4-2, IEC 60255-22-2 and ANSI 37.90.3-2001 8 kV 15 kV
Radio frequency interference tests: • Conducted, common mode  • Radiated, amplitude-modulated  • Radiated, pulse-modulated	According to IEC 61000-4-6 and IEC 60255-22-6 (2000) 10 V (rms), f = 150 kHz...80 MHz According to IEC 61000-4-3 and IEC 60255-22-3 (2000) 10 V/m (rms), f = 80...1000 MHz According to the ENV 50204 and IEC 60255-22-3 (2000) 10 V/m, f = 900 MHz

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(continued)

Fast transient disturbance tests: • Power outputs, energizing inputs, power supply • I/O ports	According to IEC 60255-22-4, and IEC 61000-4-4 4 kV 2 kV
Surge immunity test: • Power outputs, energizing inputs, power supply • I/O ports	According to IEC 61000-4-5 4 kV, line-to-earth, 2 kV, line-to-line 2 kV, line-to-earth, 1 kV, line-to-line
Power frequency (50 Hz) magnetic field	300 A/m continuous
Voltage dips and short interruptions	According to IEC 61000-4-11 30%/10 ms 60%/100 ms 60%/1000 ms >95%/5000 ms
Electromagnetic emission tests: • Conducted, RF emission (Mains terminal) • Radiated RF emission	According to the EN 55011 EN 55011, class A, IEC 60255-25 EN 55011, class A, IEC 60255-25
CE compliance	Complies with the EMC directive 89/336/EEC

**Insulation test**

Dielectric tests • Test voltage	According to IEC 60255-5 2 kV, 50 Hz, 1 min
Impulse voltage test • Test voltage	According to IEC 60255-5 5 kV, unipolar impulses, waveform 1.2/50 Ms, source energy 0.5 J
Insulation resistance measurements • Isolation resistance	According to IEC 60255-5 >100 M $\Omega$ , 500 V DC

**Mechanical tests**

Vibration tests (sinusoidal)	According to IEC 60255-21-1, class I
Shock and bump test	According to IEC 60255-21-2, class I

**Data communication**

Front interface: • Optical connection (infrared) via the front communication cable (1MRS050698) • SPA bus protocol • 9.6 or 4.8 kbps (9.6 kbps with front communication cable)
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## Protection functions

### Stage 0>

Feature	Value
Set safe stall time, $t_{ox}$	2..0...120 s <sup>a)</sup>
Set ambient temperature, $T_{amb}$	0...70 °C
Set restart inhibit level, $\theta_{i>}$	20...80%
Set prior alarm level, $\theta_a>$	50...100%
Trip level, $\theta_t>$	100%
Time constant multiplier, $K_c$	1...64
Weighting factor, $p$	20...100%
Operate time accuracy: • $>1.2 \times I_n$	$\pm 5\%$ of the set operate time or $\pm 1$ s

a) The setting step is 0.5.

### Stages Is>


Feature	Value
Set start value, $I_s>$ • At definite-time characteristic	1.00...10.0 $\times I_n$
Start time, typical	55 ms
Time/current characteristics • Definite time operate time, $t_s>$	0.30...80.0 s
Resetting time, typical/maximum	35/50 ms
Retardation time	30 ms
Drop-off/start ratio, typical	0.96
Operate time accuracy • At definite-time characteristic	$\pm 2\%$ of the set operate time or $\pm 25$ ms
Operation accuracy	$\pm 3\%$ of the start value



Stage  $I_s^2 \times t_s$  and stage  $I_s>$  cannot be used at the same time.

### Stage $I_{s2} \times t_s$

Feature	Value
Set start-up current motor, $I_{s2}$	$1.00 \dots 10.0 \times I_n$
Start time, typical	
• At start criterion $I_L > I_{s2}$	100 ms
Set start-up time for motor, $t_{s2}$	$0.30 \dots 80.0$ s
Resetting time, typical/maximum	180/250 ms
Drop-off/pick-up ratio, typical	
• At start criterion $I_L > I_{s2}$	0.96
Operation accuracy	$\pm 10\%$ of the calculated operate time $\pm 0.2$ s
Shortest possible operate time	300 ms

 Stage  $I_{s2} \times t_s$  and stage  $I_{s1} >$  cannot be used at the same time.

### Stage $I_{>>}$

Feature	Value
Set start value, $I_{>>}$	
• At definite-time characteristic	$0.50 \dots 20.0 \times I_n$
Start time, typical	50 ms
Time/current characteristic	
• Definite time operate time, $t_{0>>}$	$0.05 \dots 300$ s
Resetting time, typical/maximum	40/50 ms
Retardation time	30 ms
Drop-off/pick-up ratio, typical	0.96
Operate time accuracy at	
• Definite-time characteristic	$\pm 2\%$ of the set operate time or $\pm 25$ ms
Operation accuracy	$\pm 3\%$ of the set start value

### Stage $I_{<}$

Feature	Value
Set start value, $I_{<}$	
• At definite-time characteristic	$30 \dots 80\% I_n$
Start time, typical	300 ms
Time/current characteristic	
• Definite time operate time, $t_{<}$	$2 \dots 600$ s
Resetting time, typical/maximum	300/350 ms
Drop-off/pick-up ratio, typical	1.1
Inhibition of $I_{<}$	$< 12\% I_n$
Operate time accuracy	
• At definite-time characteristic	$\pm 3\%$ of the set operate time or 100 ms
Operation accuracy	$\pm 3\%$ of the set start value or $+0.5\% I_n$

### Stage I<sub>0</sub>>

Feature	Value
Set start value, I <sub>0</sub> > • At definite-time characteristic	1.0...100% I <sub>n</sub>
Start time, typical	50 ms
Time/current characteristic • Definite time operate time, t<	0.05...300 s
Resetting time, typical/maximum	40/50 ms
Retardation time	30 ms
Drop-off/pick-up ratio, typical	0.96
Operate time accuracy • At definite-time characteristic	±2% of the set operate time or ±25 ms
Operation accuracy • 1.0...10.0% I <sub>n</sub> • 1.0...100% I <sub>n</sub>	±5% of the set start value ±3% of the set start value

### Stage I<sub>2</sub>>

Feature	Value
Set start value, I <sub>2</sub> > • At IDMT characteristic	0.10...0.50 x I <sub>n</sub>
Start time, typical	100 ms
Time/current characteristic • IDMT time constant, K <sub>2</sub>	5...100
Resetting time, typical/maximum	130/200 ms
Drop-off/pick-up ratio, typical	0.95
Operate time accuracy • I <sub>2</sub> > + 0.065...4.0 x I <sub>n</sub>	±5% of the calculated operate time or ±100 ms
Operation accuracy	±5% of the set start value
Inhibition of I <sub>2</sub> >	I < 0.12 x I <sub>n</sub> or I > 4.0 x I <sub>n</sub>

### Stage REV

Feature	Value
Trip value	NPS ≥75% of the maximum phase current
Time/current characteristic • Definite time operate time	220 ms ±50 ms
Resetting time, typical	100...200 ms
Drop-off/pick-up ratio, typical	0.95

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**Stage  $\Sigma_{tsi}$**

Feature	Value
Set restart inhibit value, $\Sigma_{tsi}$	5...500 s
Countdown rate of start-up time counter, $\Delta\Sigma_{ts}/\Delta t$	2...250 s/h

**Stages ThA> and ThB>**

Feature	Value
Operate time accuracy at definite-time characteristic	$\pm 3\%$ of the set operate time or 200 ms <sup>a)</sup>
RTD sensors	
Set alarm value, Ta1...6>	0...200 °C
Operate time, ta1...6>	1...100 s
Set trip value, Tp1...6>	0...200 °C
Operate time, tp1...6>	1...100 s
Hysteresis	5 °C
Operation accuracy	$\pm 1$ °C ( $\pm 3$ °C for Cu10)
Thermistors	
Set trip value, Thp1> and Thp2>	0.1...15.0 k $\Omega$
Operate time	2 s
Operation accuracy	$\pm 1\%$ of the setting range

a) Note the response time of the RTD card (<8s).

**CBFP**

Feature	Value
Set operate time	0.10...60.0 s
Phase-current threshold for external triggering of the CBFP	
• Pick-up/drop-off	0.13/0.11 x $I_n$



## 12. Mounting methods

Using the appropriate mounting accessories, the standard relay case for the RE\_ 610 series relays can be flush mounted, semi-flush mounted or wall mounted. The flush mounted and wall mounted relay cases can also be mounted in a tilted position (25°) by using special accessories. Further, the relays can be mounted in any standard 19" instrument cabinet by means of 19" mounting panels available with cut-outs for one or two relays. Alternatively, the relays can be mounted in 19" instrument cabinets by means of 4U Combiflex equipment frames. For the routine testing purposes, the relay cases can be equipped with test switches, type RTXP 18, which can be mounted side by side with the relay cases.

Mounting methods:

- Flush mounting
- Semi-flush mounting
- Semi-flush mounting in a 25° angle
- Rack mounting
- Wall mounting
- Mounting to a 19" equipment frame
- Mounting with a RTXP 18 test switch to a 19" rack

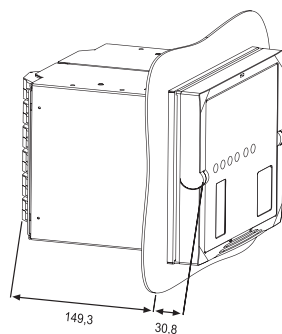


Fig. 4 Flush mounting

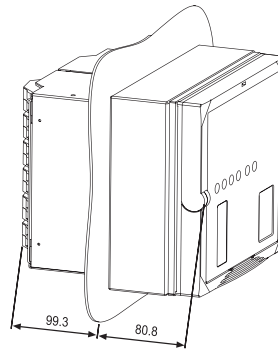


Fig. 5 Semi-flush mounting

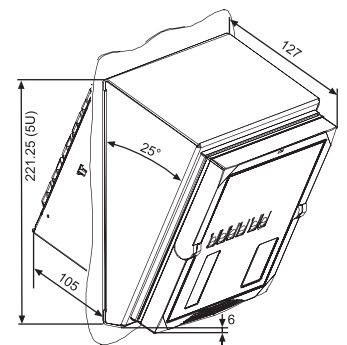


Fig. 6 Semi-flush mounting in a 25° angle

## 13. Relay case and relay plug-in unit

As a safety measure, the relay cases for the current measuring relays are provided with automatically acting contacts for short-circuiting the CT secondaries, when a relay plug-in unit is withdrawn from the relay case. In addition, the relay case is provided with a mechanical coding system to prevent the current measuring relay plug-in units from being inserted into a case for a voltage relay unit and vice versa, i.e. the relay cases are associated to a certain type of relay plug-in unit.

There is, however, a universal relay case available, which is not associated to a certain plug-in unit type. When a relay plug-in unit is plugged into such a relay case for the first time, the relay case will automatically adapt to that particular relay type, i.e. the short-circuiting contacts will be activated as well as the mechanical blocking system. Hereafter, the relay case is permanently associated to a certain relay type.

## 14. Selection and ordering data

When ordering protection relays and/or accessories, please specify the following information: order number, HMI language set number and quantity. The order number identifies the protection relay type and hardware and is labelled on the marking strip under the lower handle of the relay.

Use the ordering key information in Fig. 7 to generate the order number when ordering complete protection relays.

REM610		□	□	□	□	C	□	□	□
<b>Revision</b>									
Current revision						C			
<b>Phase-current inputs:</b>									
5 = 5A						5			
1 = 1A						1			
<b>Earth-fault current input:</b>									
5 = 5A						5			
1 = 1A						1			
<b>Power supply:</b>									
H = 100-240 V AC/110-250 V DC, 2xDI (110/125/220/250 V DC), 3xPO 2xSO						H			
L = 24-60 V DC, 2xDI (24/48/60/110/125/220/250 V DC), 3xPO, 2xSO						L			
<b>RTD/Thermistor module:</b>									
M = included						M			
N = none						N			
<b>Communication module:</b>									
P = plastic fiber						P			
G = plastic and glass fiber						G			
R = RS-485						R			
N = none						N			
<b>Language set:</b>									
01 = (IEC) English, Svenska, Suomi						01			
02 = (IEC) English, Deutsch, Francais, Italiano, Español, Polski						02			
11 = (ANSI) English, Español, Portugese						11			

Fig. 7 Ordering key for complete relays

Use the ordering key information in Fig. 8 to generate the order number when ordering spare units.

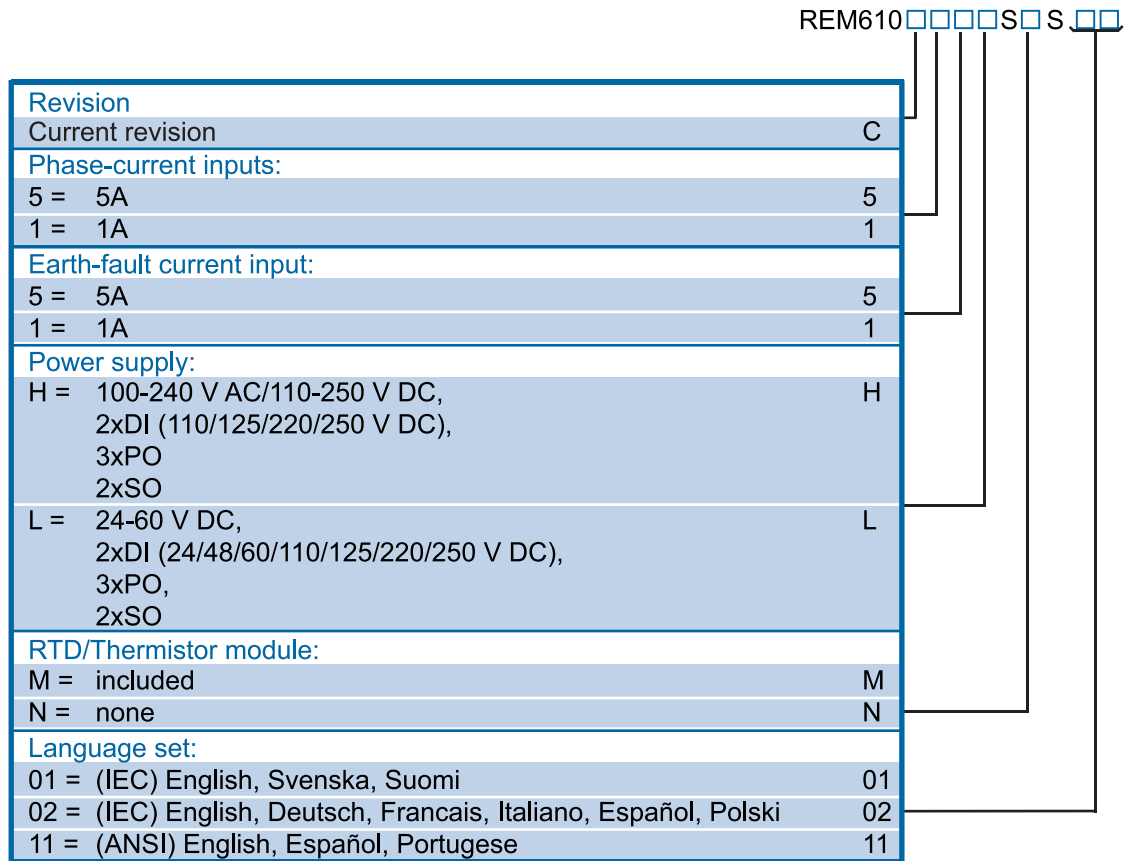


Fig. 8 Ordering key for spare units

## 15. Accessories and tools

Item	Order nr
<b>Cables:</b>	
Front communication cable	1MRS050698
<b>Mounting accessories:</b>	
Semi-flush mounting kit	1MRS050696
Inclined semi-flush mounting kit	1MRS050831
19 " rack mounting kit with cutout for one relay	1MRS050694
19 " rack mounting kit with cutout for two relays	1MRS050695
Surface mounting frame	1MRS050697
Mounting bracket for RTXP 18	1MRS061207
Mounting bracket for 4U high Combiflex equipment frame	1MRS061208
<b>Test switches:</b>	
Test switch RTXP 18	1MRS050783
<b>Optional communication cards:</b>	
Plastic fibre	1MRS050889
RS-485	1MRS050892
Plastic and glass fibre	1MRS050891
<b>RE_ 610 universal cases:</b>	
Empty universal relay case for RE_ 610	1MRS050904

Configuration, setting and SA system tools	Version
CAP 501 Relay Setting Tool CAP 50	v. 2.4.0-1 or later
CAP 505 Relay Setting Tool CAP 50	v. 2.4.0-1 or later
SMS 510 Substation Monitoring System	SMS 510 v.1.2.0-1 or later
LIB 510 Library for MicroSCADA v. 8.4.4	LIB 510 v. 4.0.5-3 or later

## 16. Terminal diagram

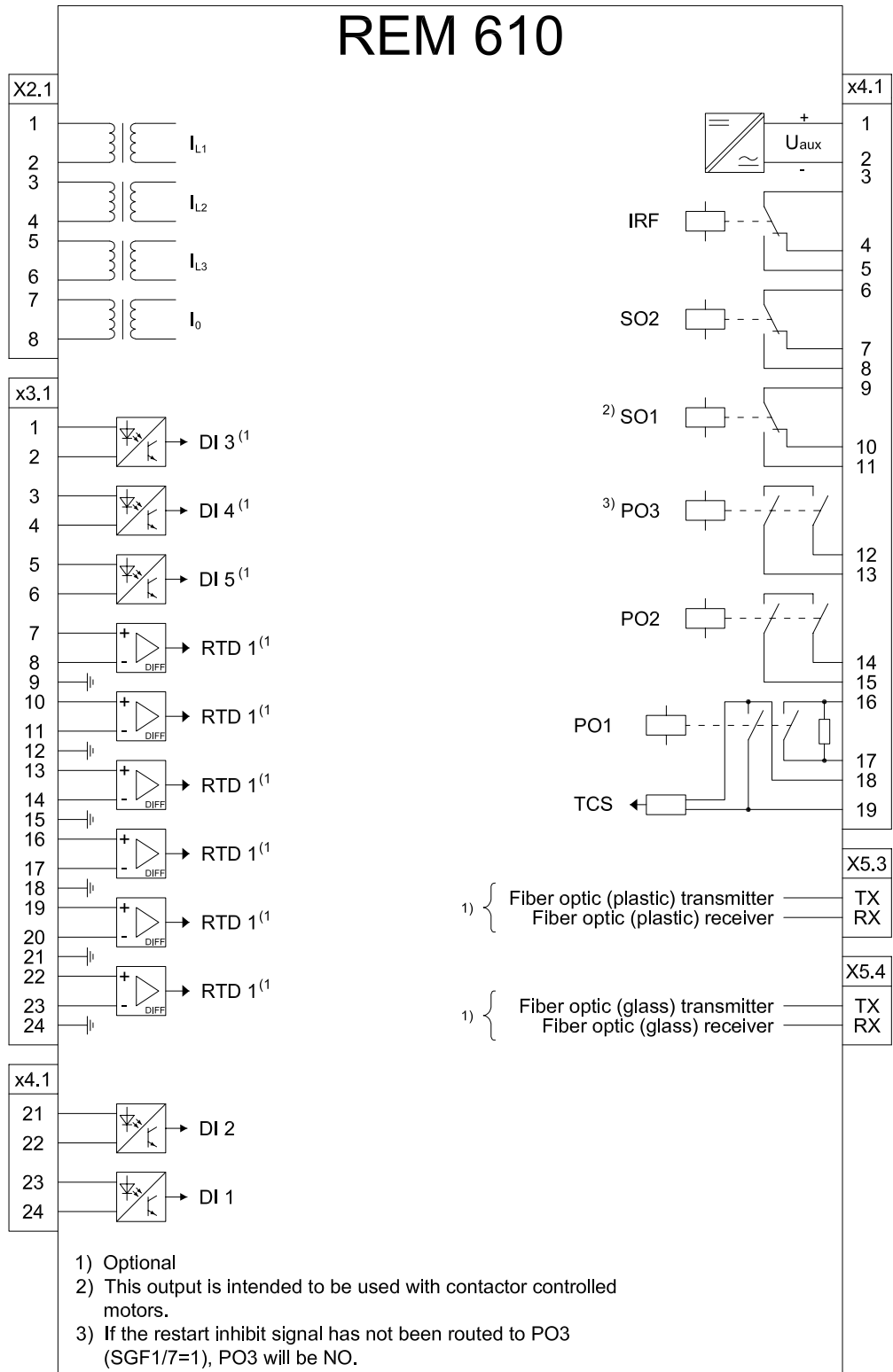


Fig. 9 Terminal diagram of REM 610

## 17. References

The [www.abb.com/substationautomation](http://www.abb.com/substationautomation) portal offers you information about the distribution automation product and service range.

You will find the latest relevant information on the REF 610 protection relay on the [product page](#).

The download area on the right hand side of the web page contains the latest product

documentation, such as technical reference manual, installation manual, operators manual, etc. The selection tool on the web page helps you find the documents by the document category and language.

The Features and Application tabs contain product related information in a compact format.

Product Guide > Medium Voltage Products > Protection and Control (Distribution) > Machine Protection > Motor Protection Relay > REM 610

### Motor Protection Relay REM 610

**General** | Service & Support | Application | Features | Contacts

The motor protection relay REM 610 is part of the RE\_ 610 series of numerical relays for the protection and supervision of utility substations, and industrial switchgear and equipment.

The motor protection relay REM 610 is primarily targeted at protecting large asynchronous low-voltage motors and small and medium-sized high-voltage asynchronous motors. REM 610 handles electrical fault conditions during motor start up, normal operation, idling, and cooling down at standstill, e.g. in pump, fan, mill or crusher applications. The relay can be used with both circuit-breaker controlled and contactor-controlled drives. REM 610 can also be used for the protection of cables feeders and distribution transformers that require thermal overload protection besides overcurrent, earth-fault and phase unbalance protection.

The numerical motor protection relays support a wide range of standard communication protocols, among them the IEC 61850, IEC 60870-5-103, Modbus, and Profibus.

For further information, see Features and Application tabs.

**Downloads** [Show options for filtering result](#)

Application description	Language	Size
<a href="#">Motor with power factor correction capacitor, Relay settings, Application and setting guide</a>	English	0.83 MB
<b>Article</b> <a href="#">Disturbance-free MV power distribution</a>	English	0.33 MB
<b>Brochure</b> <a href="#">RE_ 610, Industrial Power System Protection, 8-page leaflet</a>	English	1.41 MB
<b>Certificate</b> <a href="#">REM 610, Motor Protection Relay, Environmental Information</a>	English	0.02 MB

Fig. 10 Product page





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